

Cocurrently-Cooled Fixed-Bed Reactors: A Simple Approach to Optimal Cooling Design

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Wall-cooled fixed-bed reactors are commonly used in industrial plants to carry out highly exothermic reactions. Due to the presence of important heat effects, these units present the well known problems of pronounced maxima in the axial temperature profile (hot spots) and high parametric sensitivity.

The safe design of these reactors has been intensively studied during the last decades. Two extensive reviews have recently been published on the subject by Puszyński et al. (1981) and Froment (1984). Except for the works related to autothermal reactors, most researchers assume that the coolant temperature profile is constant. Only recently has attention been paid to the influence of the coolant-zone design on reactor operation. Luss and Medellin (1972) and Akella and Lee (1983) studied the behavior of countercurrently-cooled nonisothermal tubular reactors, while the cocurrent scheme has been studied by, among others, Degnan and Wei (1979), Soria López et al. (1981), and Hosten and Froment (1986). More complex coolant flow configurations have been studied by Smith and Banchemo (1973) and McGreavy and Dunbobbin (1978).

In a recent contribution, Borio et al. (1989) analyzed, comparatively, three basic cooling schemes: countercurrent, cocurrent and perfectly mixed coolant. They concluded that for equivalent production rates, the cocurrent operation is the one which yields the lowest values for the maximum temperature and parametric sensitivity, provided an adequate selection for the coolant flow rate can be made.

In the present work, following the same guidelines, a simple expression is developed to predict the coolant flow rate value leading to conditions of maximum attainable safety (minimum hot spot and low parametric sensitivity). This analytical tool allows the solution of this optimization problem without the need to resort to a laborious iterative simulation of the unit.

Definition of the Safety Problem

The reactor model presented by Borio et al. (1989) will be used here. They analyzed a multitubular fixed-bed reactor for phthalic anhydride production, cooled by means of a liquid of very high thermal conductivity. The highly exothermic reaction of *o*-xylene oxidation with excess air is assumed to be a pseudo-first-order irreversible one. Finally, as often occurs in practice, both the temperatures of the reactants and of the coolant medium are considered to be equal at the inlet of the reaction section.

The above described model results in the following set of ordinary differential equations, where the values of the parameters needed in the calculations are those reported by van Welsenaere and Froment (1970) and Soria López et al. (1981):

$$-\frac{dp_A}{dz} = A p_A k_\infty \exp(-a/T) \quad (1)$$

$$\frac{dT}{dz} = B p_A k_\infty \exp(-a/T) - C(T - T_c) \quad (2)$$

$$\frac{dT_c}{dz} = D(T - T_c) \quad (3)$$

where, for

$$\begin{aligned} z = 0 \quad p_A &= p_{A_0}, \quad T = T_c \\ z = j \quad T_c &= T_{c_j}, \quad \text{with } \begin{cases} j = 0 & \text{cocurrent} \\ j = L & \text{countercurrent} \end{cases} \end{aligned}$$

Borio et al. (1989) solved Eqs. 1–3 together with the set of three coupled differential equations for the parametric sensitiv-

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ity at each point of the reactor length. From the simulation results they demonstrated that the cocurrent arrangement exhibits lower hot spots and lower parametric sensitivities than those found in the alternative coolant schemes, yielding shorter reactors and a safer operation. Also, there are two particular values of the coolant flow rate, both in the cocurrent scheme, which, for a given production rate, respectively minimize the maximum reactant temperature and the maximum parametric sensitivity.

All this is illustrated in Figure 1, where the maximum temperature in the reactor tube (T_M) and the extreme in the axial profile of the reactant temperature sensitivity, with respect to the inlet coolant temperature (S^*), are plotted against Wc^{-1} . A first inspection reveals that the minimum of the T_M curve is much more pronounced than that of the S^* curve. Due to this, the reactor should operate ideally at the value of Wc indicated as Wc_{opt} , provided that it yields both minimum T_M and an S^* very close to its lowest value, S_m^* . Therefore, in a first approach, Wc_{opt} can be defined as the optimal design for the cooling side from the safety standpoint.

However, the calculation of Wc_{opt} is not a trivial problem. In fact, a different Wc_{opt} is found for each set of values for the reactor size and the variables which determine the production rate (G_g , p_{A0} , and x_L). To illustrate this, the influence of the reactor length on Wc_{opt} is shown in Figure 2 for the same production requirements. In principle, a numerical solution to the problem is needed, e.g., by means of an optimization algorithm which, at each step, would require a reactor simulation in order to evaluate the objective function, T_M . Moreover, the fact of imposing a given production rate gives rise to a boundary value problem, introducing an additional complexity to the calculation.

In the following, a method is described which constitutes a direct and simple way to approximate this problem. As a previous step, the relationship between the minimum T_M and the isothermicity conditions, which is necessary to the present development, will be discussed.

Theoretical Minimum for T_M

Assume a tubular reactor where a first-order reaction takes place and where its dimensions, the flow rate of reactants, and

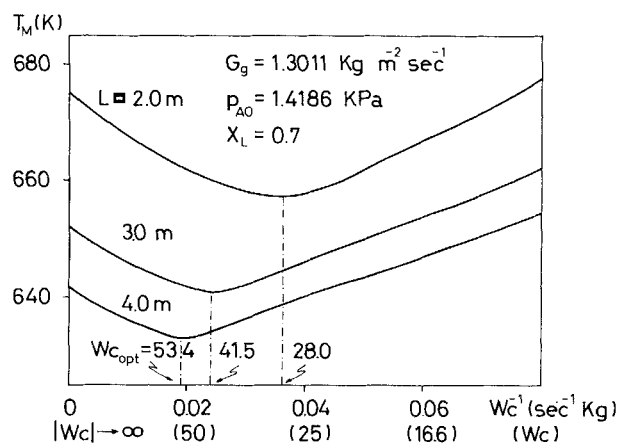


Figure 2. T_M vs. Wc^{-1} curves at conditions of constant production rate for different reactor lengths.

the outlet conversion are given. If the desired objective is to minimize T_M , it can be easily proved that the isothermal temperature profile is the optimum one.

For the particular case of wall-cooled fixed-bed reactors, Degnan and Wei (1979) deduced that the isothermal operation is only possible: a) under a cocurrent scheme and b) if independent preheating of the reactant stream is available ($T_o \neq T_{c0}$). In this case, from Eqs. 1–3 the theoretical isothermal operation will be held at:

$$T_i = \frac{a}{\ln(A k_a/D)} \quad (4)$$

For the system to work under this isothermal operation, however, it is also necessary to fix the following inlet conditions:

$$T_o = T_i \quad (5)$$

$$Tc_o + \frac{BD}{AC} p_{A0} = T_i \quad (6)$$

In order to select, from the infinite number of theoretically possible isothermal operations, the one which yields a given outlet conversion, x_L , the parameter D in Eq. 4 must satisfy the following expression:

$$D = \frac{1}{L} \ln \left[\frac{1}{1 - x_L} \right] \quad (7)$$

Therefore, any nonisothermal operation giving the same conversion, x_L , for the same value of the residence time of the reactants ($A \cdot L = \text{constant}$), must exhibit a portion of the reactor length with temperatures higher than T_i . From this analysis it can be concluded that with the industrial designs which do not include the possibility of independently preheating the reactant stream, the problem of minimizing T_M is equivalent to reducing to a minimum the difference between T_M and T_i .

Approximation to the Maximum Safety Design

The problem of an optimum cooling design from the safety standpoint, will be discussed within the framework of the non-isothermal operation, which is characteristic of industrial condi-

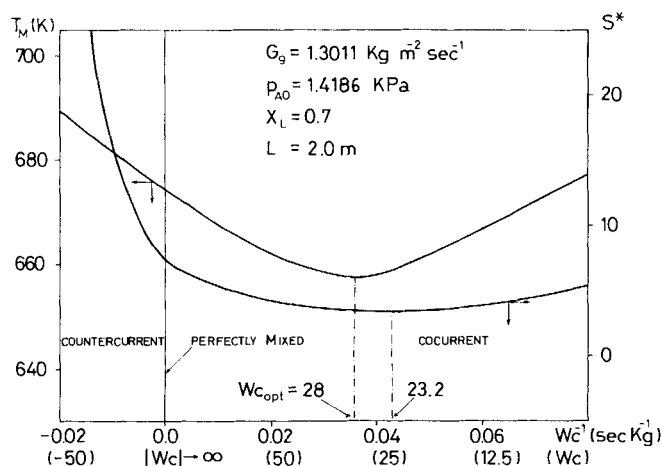


Figure 1. T_M and S^* vs. Wc^{-1} curves at conditions of constant production rate for a fixed reactor length.

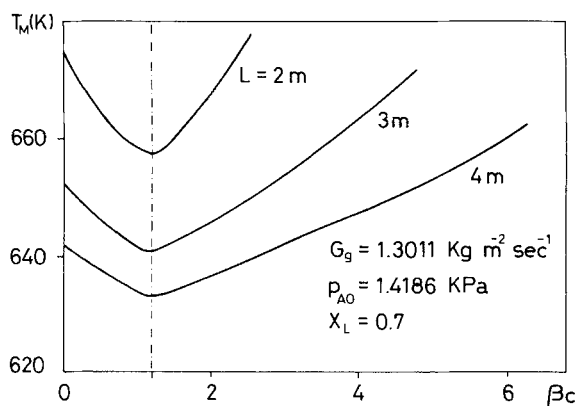


Figure 3. T_M vs. β_c curves at conditions of constant production rate for different reactor lengths.

tions. It may be convenient at this point to introduce a dimensionless heat-loss coolant parameter, $\beta_c = DL$. From the definition of D , β_c can be shown to be inversely proportional to the coolant flow rate, and can be substituted for Wc^{-1} in the abscissa axis of Figure 2. On doing this, as in Figure 3, a first inspection reveals that the T_M curves corresponding to different reactor lengths present their minima, approximately, at a unique value of the abscissa. A similar behavior is found when the effect of changes in other operation variables is analyzed. This is illustrated in Figures 4 and 5, where T_M vs. β_c curves are drawn for different values of the reactants' flow rate and the inlet partial pressure, respectively.

A second aspect of interest is that the β_c values corresponding to the minima of the T_M curves are practically coincident in the cases of Figures 3 to 5, which have the same outlet conversion ($x_L = 0.7$) in common. Consequently, the optimization problem could be reformulated as follows: find the optimum value of the coolant flow rate, Wc_{opt} (or its correspondent, $\beta_{c_{opt}}$) which for a given conversion, x_L , leads to a minimum for the maximum temperature (T_{M_m}). In other words, the problem can be reduced to finding $\beta_{c_{opt}}$ as a function of x_L .

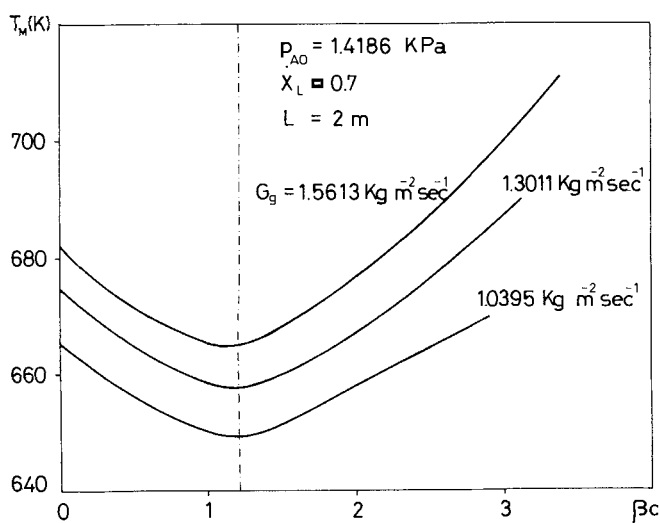


Figure 4. T_M vs. β_c curves at different specific mass flow rates.

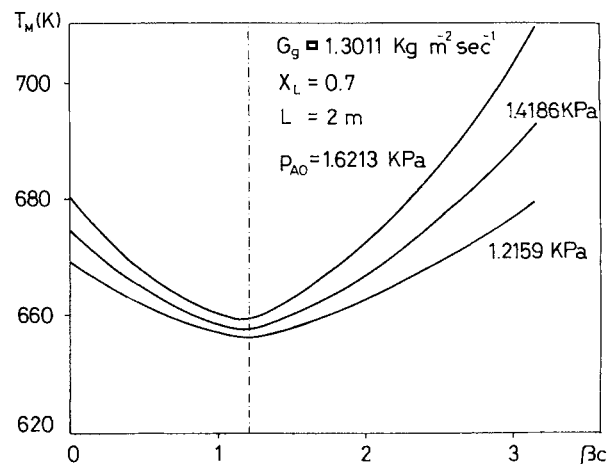


Figure 5. T_M vs. β_c curves at different inlet partial pressures.

In the previous section it was stated that for prespecified inlet conditions, the ideal isothermal operation is the one which leads to the thermal profile with minimum T_M . Therefore, it looks reasonable to investigate whether the coolant parameters, β_c , correspondent to the equivalent isothermal operation, is an adequate approximation to the optimal cooling design defined above (equivalent isothermal operation can be defined as the one which, starting from the same reactant mass flow rate, leads to the same conversion, x_L , in the same total length, L).

Assuming the previous statement is correct, the following expression can be derived from Eq. 7:

$$\beta_{c_{opt}} \approx \beta_{c_i} = \ln \left[\frac{1}{1 - x_L} \right] \quad (8)$$

The abscissa indicated with a dotted line in Figures 3 to 5, corresponds to the isothermal value, $\beta_{c_i} = 1.204$, which was calculated from Eq. 8 where $x_L = 0.7$. It can be seen, as expected, that this simple expression gives a good approximation of the locus of the minima of T_M . The same behavior was found for different values of x_L , as shown in Figure 6, where the minima of

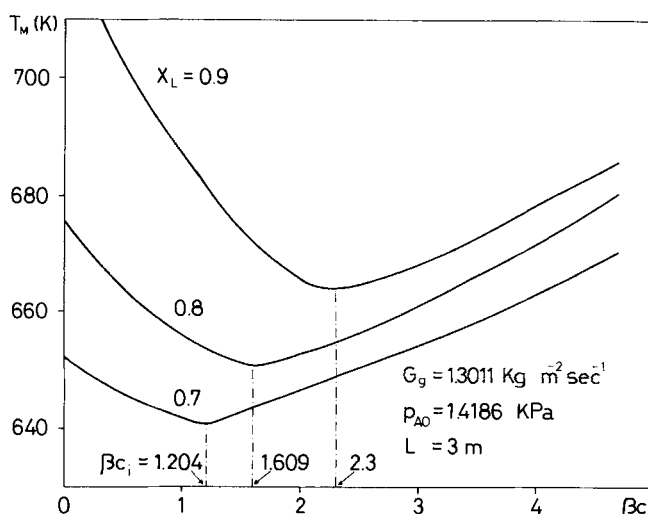


Figure 6. T_M vs. β_c curves at different outlet conversion levels.

the T_M vs. βc curves are practically coincident with the values of βc_i .

Therefore, if the cooling section is designed in the proposed way (cocurrent, $\beta c = \beta c_i$), the unit could be operated in conditions very near to those corresponding to the minimum T_M . It is also important to recall that in these conditions the values of S^* will be only slightly higher than the corresponding S_m^* .

As a sequel to a previous paper (Borio et al., 1989) where the advantages of the cocurrent configurations were demonstrated, the analytical expressions introduced here permit, in a simple and direct way, the calculation of the optimal coolant flow rate. The implementation of the proposed cooling strategy in industrial units where countercurrent or perfectly mixed cooling schemes are in current use, would lead to a significant improvement in the safety of the reactor operation.

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Notation

$a = E/R$
 $A = (\rho_b P M p_{B_0})/(G_g)$
 $B = (\rho_b(-\Delta H)p_{B_0})/(G_g c_{p_g})$
 $C = (4U)/(d_i G_g c_{p_g})$
 c_p = specific heat, $\text{KJ} \cdot \text{Kg}^{-1} \cdot \text{K}^{-1}$
 d = diameter, m
 $D = (\pi d_i t_n U)/(Wc c_p)$
 E = activation energy, $\text{KJ} \cdot \text{Kmol}^{-1}$
 G = specific mass flow rate, $\text{Kg} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$
 k_a = preexponential factor, $\text{Kmol} \cdot \text{s}^{-1} \cdot \text{Kgcat}^{-1} \cdot \text{KPa}^{-2}$
 L = total reactor length, m
 M = molecular weight of gaseous mixture, $\text{Kg} \cdot \text{Kmol}^{-1}$
 p = partial pressure, KPa
 P = total pressure, KPa
 R = universal gas constant, $\text{KJ} \cdot \text{Kmol}^{-1} \cdot \text{K}^{-1}$
 S^* = absolute extreme (max or min) of $\partial T(z)/\partial Tc_j$ curves, K/K
 t_n = number of reactor tubes
 T = temperature inside reactor tubes, K
 Tc = temperature of cooling fluid, K
 U = overall heat transfer coefficient, $\text{KW} \cdot \text{m}^{-2} \cdot \text{K}^{-1}$
 Wc = cooling mass flow rate, $\text{Kg} \cdot \text{s}^{-1}$
 x = conversion
 z = axial coordinate, m

Greek letters

βc = dimensionless cooling heat-loss parameter
 ΔH = heat of reaction, $\text{KJ} \cdot \text{Kmol}^{-1}$
 ρ = density, $\text{Kg} \cdot \text{m}^{-3}$

Subscripts

A = O-xylene
 b = bulk
 B = second component
 c = cooling medium
 g = gas
 i = isothermal operation
 j = at inlet axial position
 L = at axial position, $z = L$
 m = minimum
 M = at maximum temperature axial position
 o = at axial position, $z = 0$
 opt = optimal
 t = tube

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